

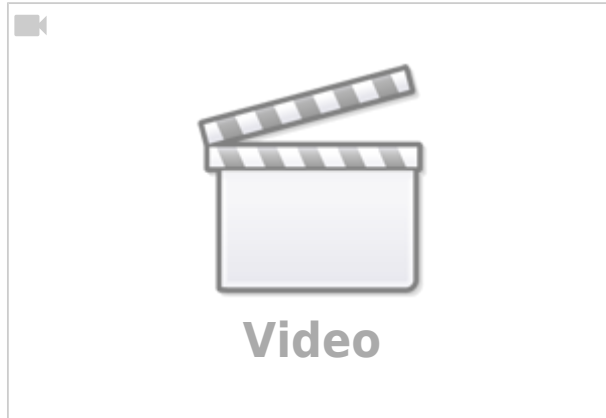
Otros



Vídeos

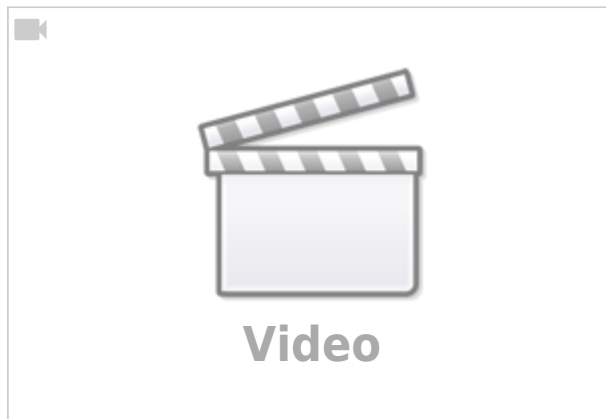
1

[Entradas y Salidas \(I\) \(28m 35s\)](#)



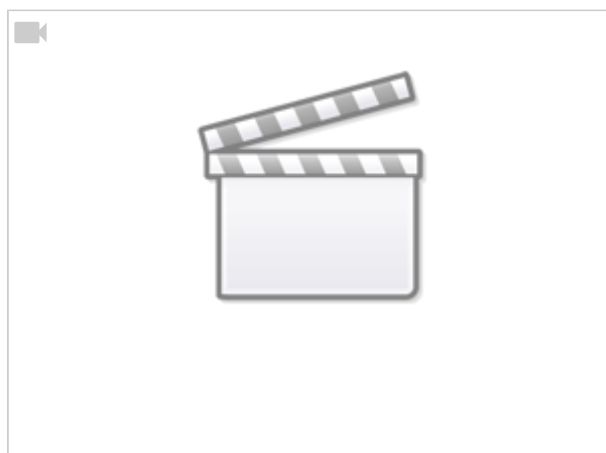
2

[Entradas y Salidas \(II\) \(42m 53s\)](#)



3

[Entradas y salidas virtuales en Robotware 6 \(14m 34s\)](#)





Video

4

[Detener o reanudar el movimiento de un robot con entradas digitales \(4m 01s\)](#)



Video

5

[Propuesta de actividad: Paletizado \(0m 43s\)](#)



Video

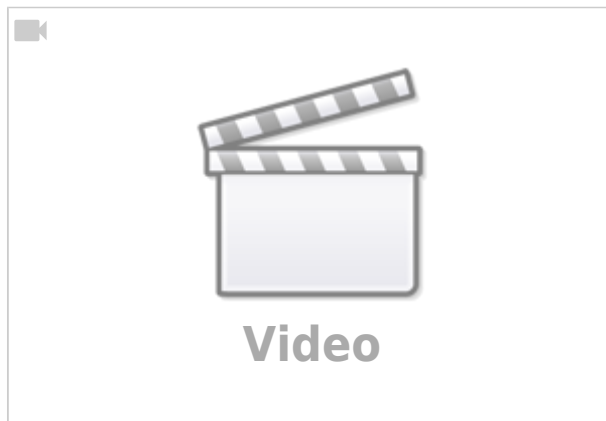
6

[Iniciación al uso de Smart Components \(34m 03s\)](#)

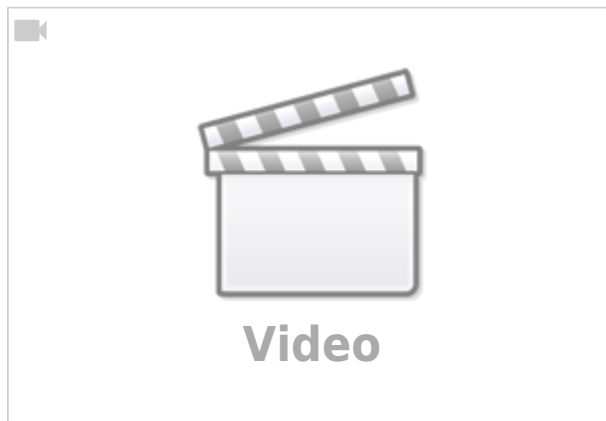


Video

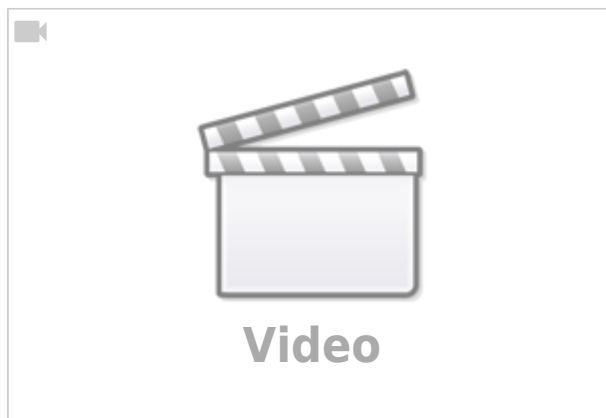
7

[Kit de Smart Components para RobotStudio \(11m 58s\)](#)

8

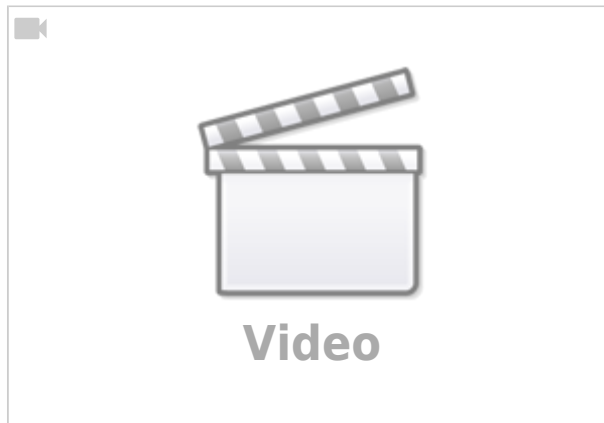
[Comunicación con WinCC Flexible mediante OPC Server \(51m 40s\)](#)

9

[Proyecto \(1\): Programando y copiando trayectorias \(19m 12s\)](#)

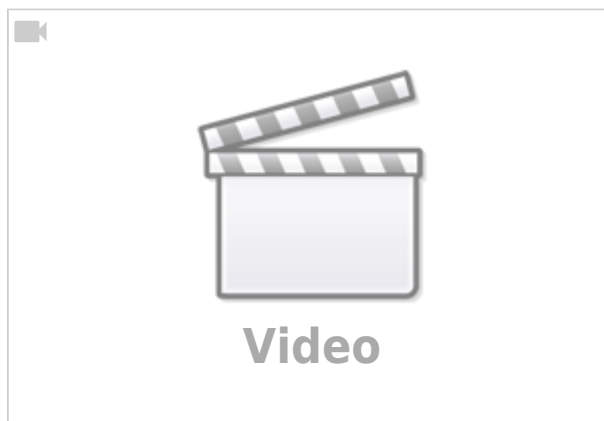
10

[Proyecto \(2\): Uso de If-Then, For, CallByVar, TPreadNumb \(21m 36s\)](#)



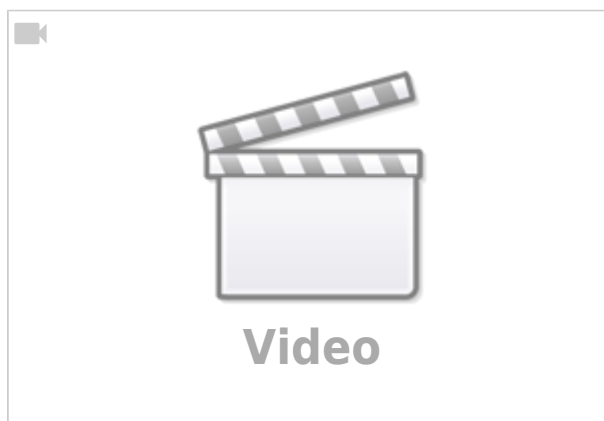
11

[Proyecto \(3\): Activar salidas digitales con SetDO \(22m 05s\)](#)



12

[Proyecto \(4\): HMI en FlexPendant con ScreenMaker \(42m 45s\)](#)



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